

CMP448: Algorithms



Lecture 01: Algorithm Analysis

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Agenda

- Analysis of Algorithms
- Insertion Sort
- Asymptotic Analysis
- Merge Sort
- Recurrences

Acknowledgment

A lot of slides adapted from the slides of Erik Demaine and Charles Leiserson

Algorithms

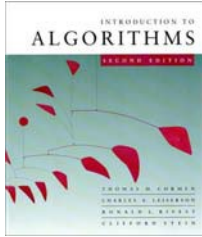
Algorithm

A computational procedure that takes some values as input and produces some values as output

Algorithm Analysis

Determining the *resources* required by the algorithm as a function of the input size.

Resources include *space* and *time*.



Why study algorithms and performance?

- Algorithms help us to understand *scalability*.
- Performance often draws the line between what is feasible and what is impossible.
- Algorithmic mathematics provides a *language* for talking about program behavior.
- Performance is the *currency* of computing.
- The lessons of program performance generalize to other computing resources.
- Speed is fun!

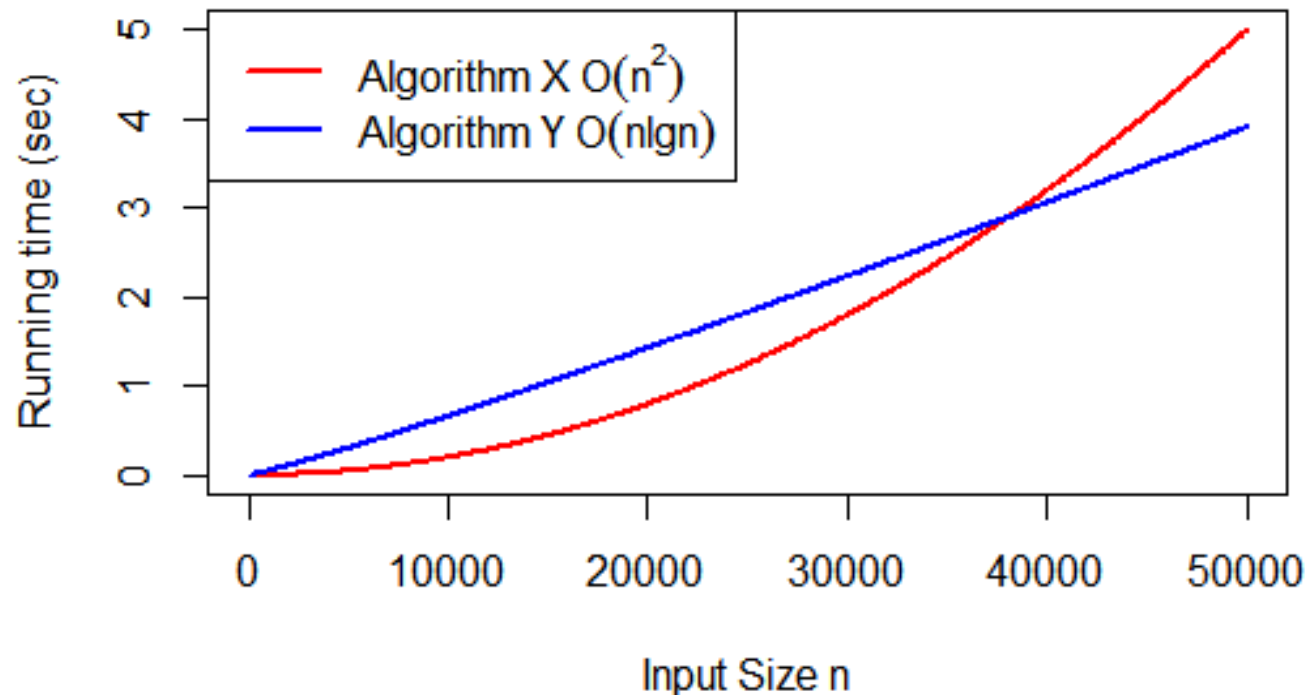
Running time

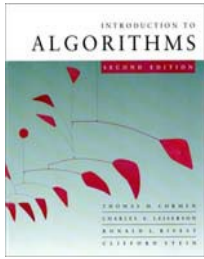
- Assume:
 - Algorithm X takes time $2n^2$ (written by best programmer) running on machine with 1000 MIPS
 - Algorithm Y takes time $50n \lg n$ (written by worst programmer) running on machine with 10 MIPS
- Running time for 10^6 numbers
 - Algorithm X takes 2000 seconds
 - Algorithm Y takes ~ 100 seconds

Complexity makes a huge difference!

Running time

- Assume:
 - Algorithm X takes time $2n^2$ (written by best programmer) running on machine with 1000 MIPS
 - Algorithm Y takes time $50n \lg n$ (written by worst programmer) running on machine with 10 MIPS





The problem of sorting

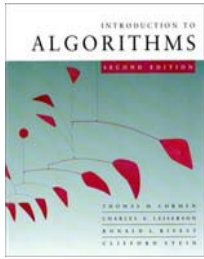
Input: sequence $\langle a_1, a_2, \dots, a_n \rangle$ of numbers.

Output: permutation $\langle a'_1, a'_2, \dots, a'_n \rangle$ such that $a'_1 \leq a'_2 \leq \dots \leq a'_n$.

Example:

Input: 8 2 4 9 3 6

Output: 2 3 4 6 8 9



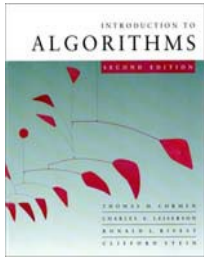
Insertion sort

“pseudocode”

```
INSERTION-SORT ( $A, n$ )   $\triangleleft A[1 \dots n]$ 
  for  $j \leftarrow 2$  to  $n$ 
    do  $key \leftarrow A[j]$ 
        $i \leftarrow j - 1$ 
       while  $i > 0$  and  $A[i] > key$ 
         do  $A[i+1] \leftarrow A[i]$ 
             $i \leftarrow i - 1$ 
        $A[i+1] = key$ 
```


Insertion Sort

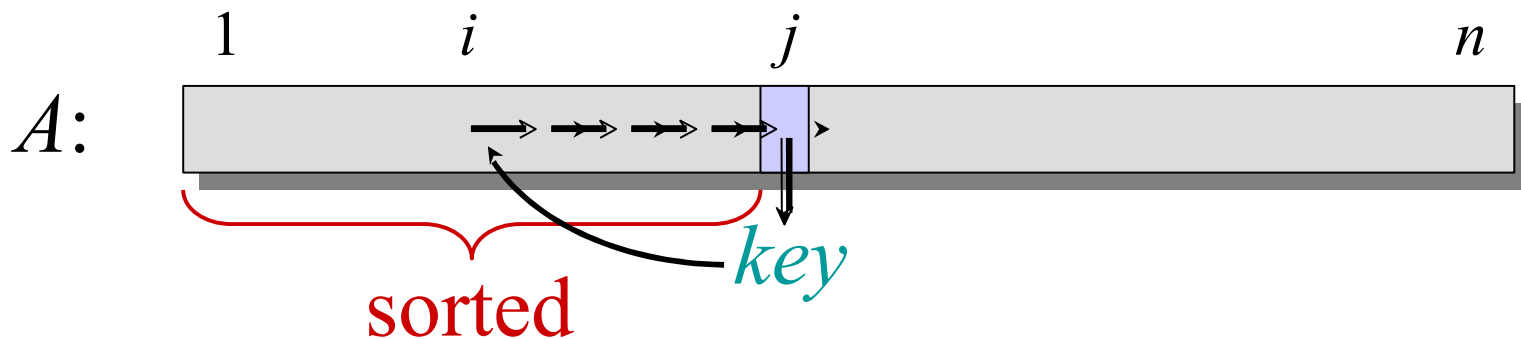
```
void insertion_sort(vector<int>& A) {
    for (int j = 1; j < A.size(); ++j) {
        int key = A[j];
        int i = j - 1;
        for (; i >= 0 && A[i] > key;) {
            A[i+1] = A[i--];
        }
        A[i+1] = key;
    }
}
```

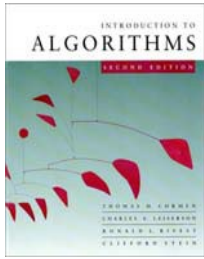


Insertion sort

“pseudocode”

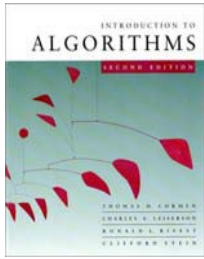
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```





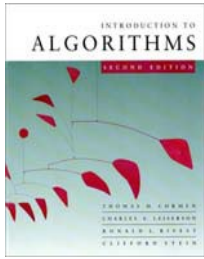
Example of insertion sort

8 2 4 9 3 6



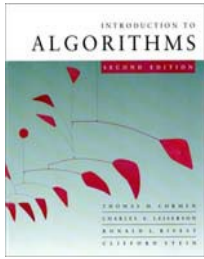
Example of insertion sort



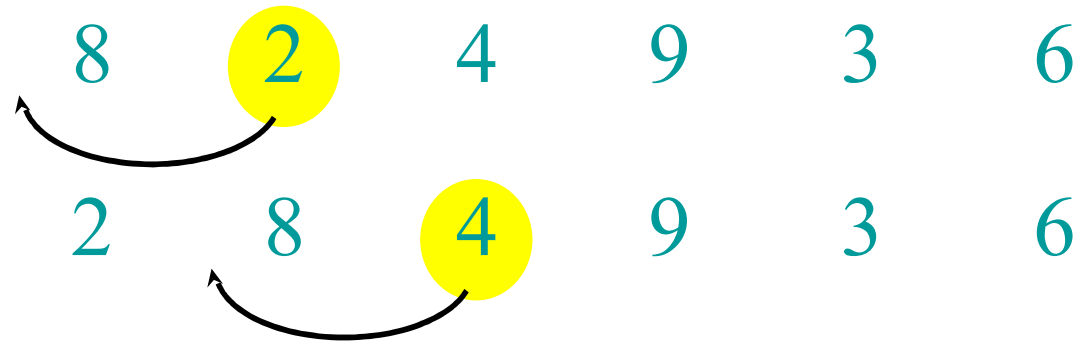


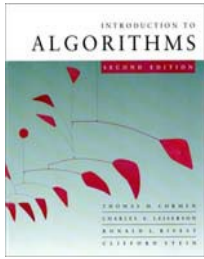
Example of insertion sort



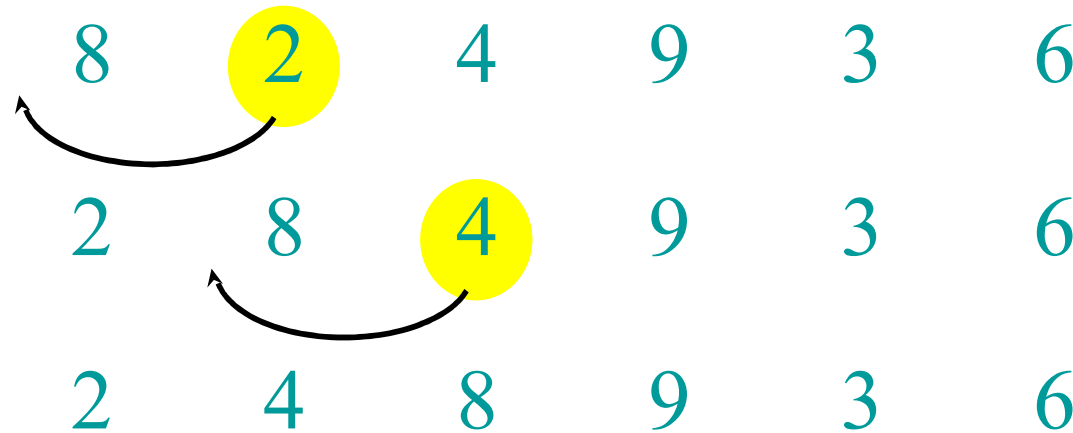


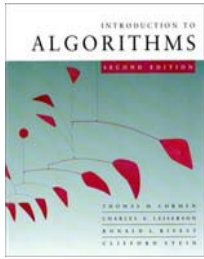
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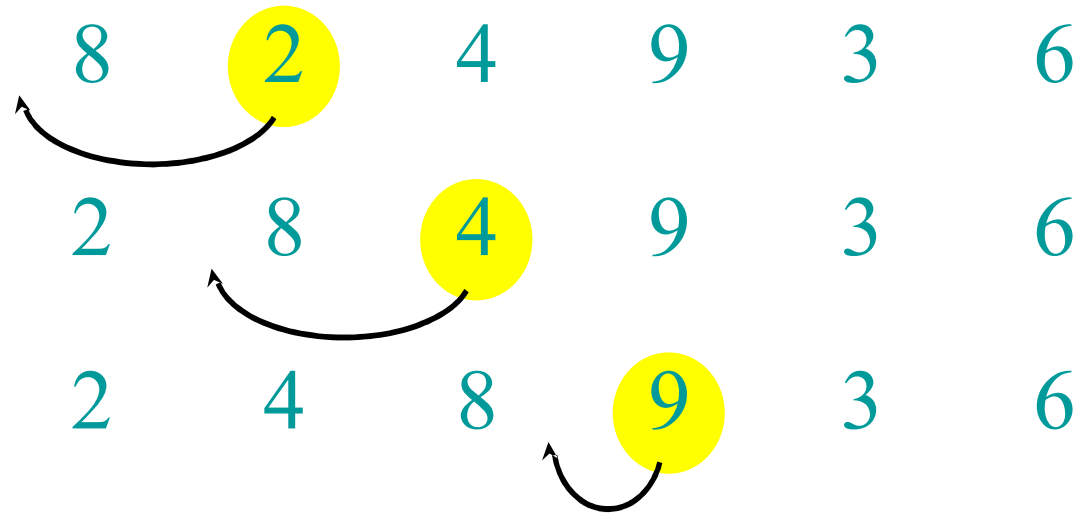


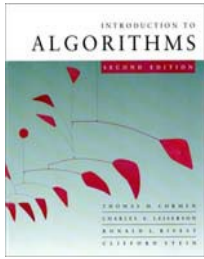
Example of insertion sort



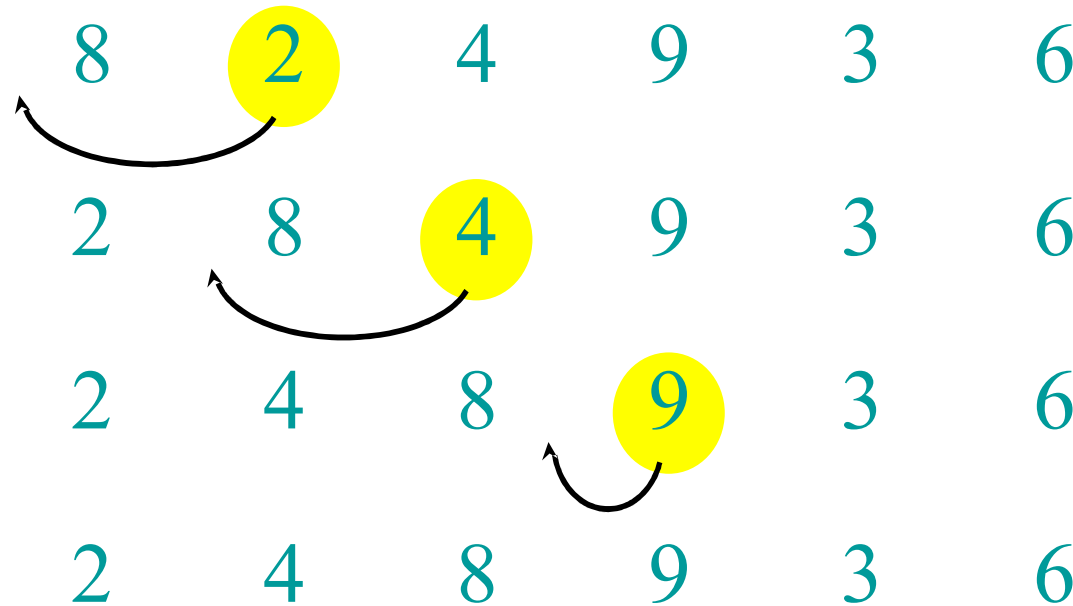


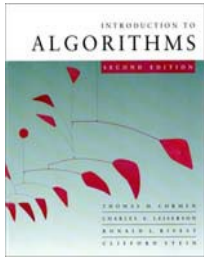
Example of insertion sort



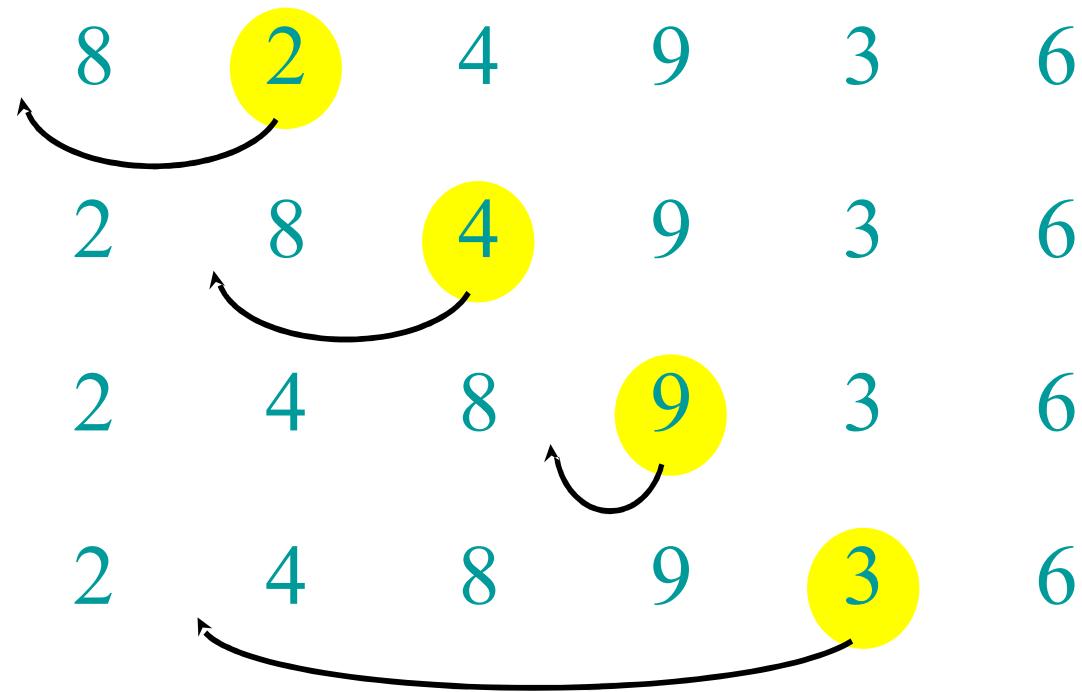


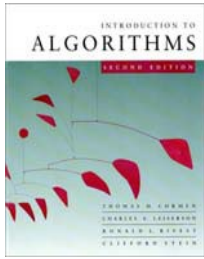
Example of insertion sort



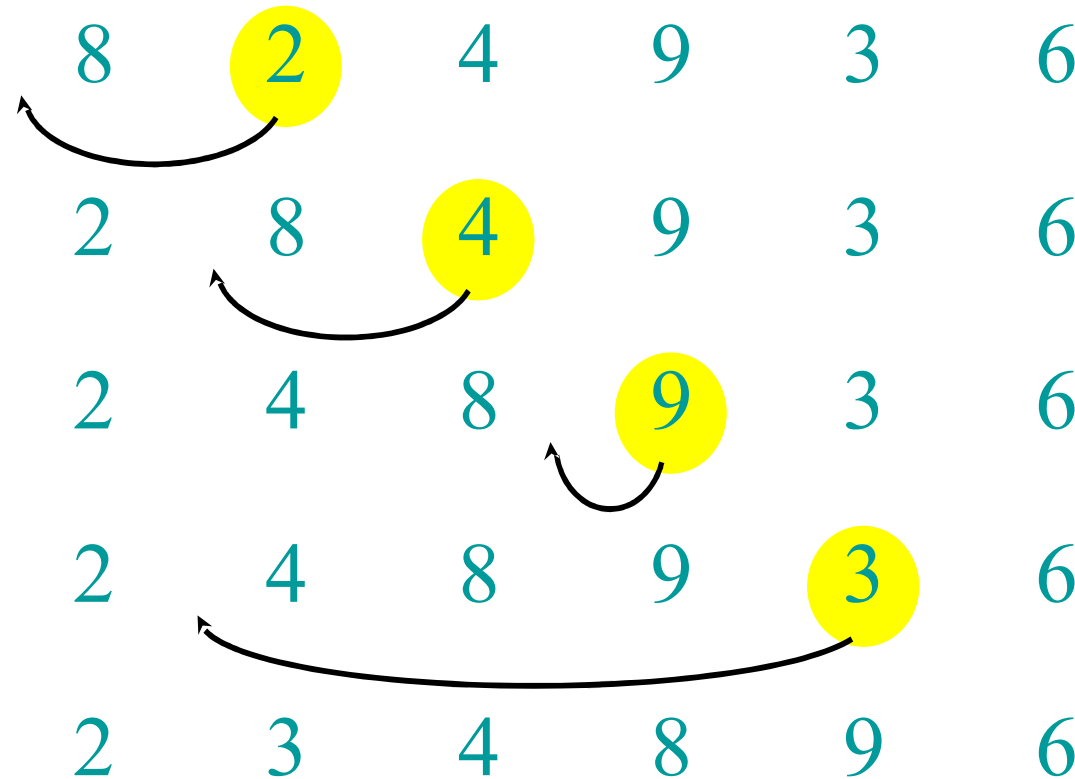


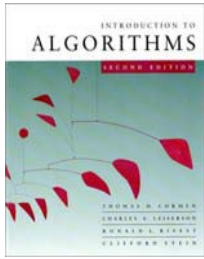
Example of insertion sort



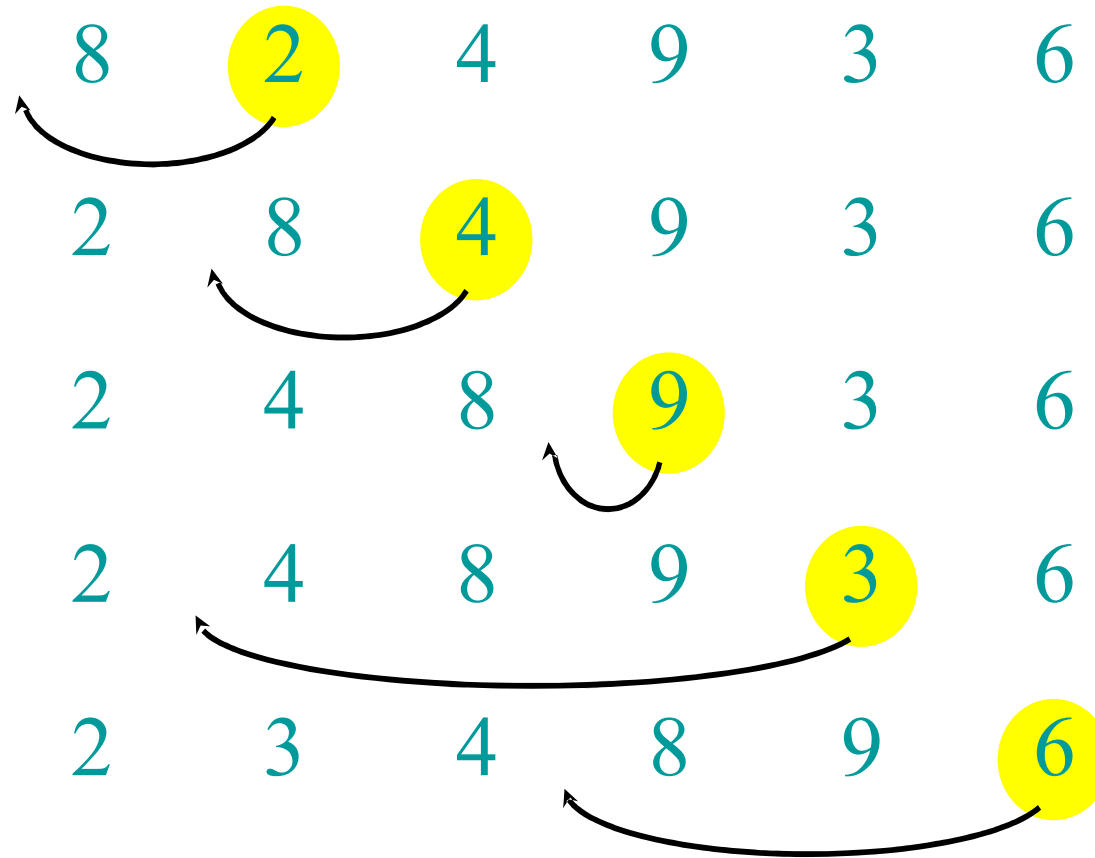


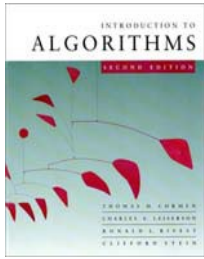
Example of insertion sort



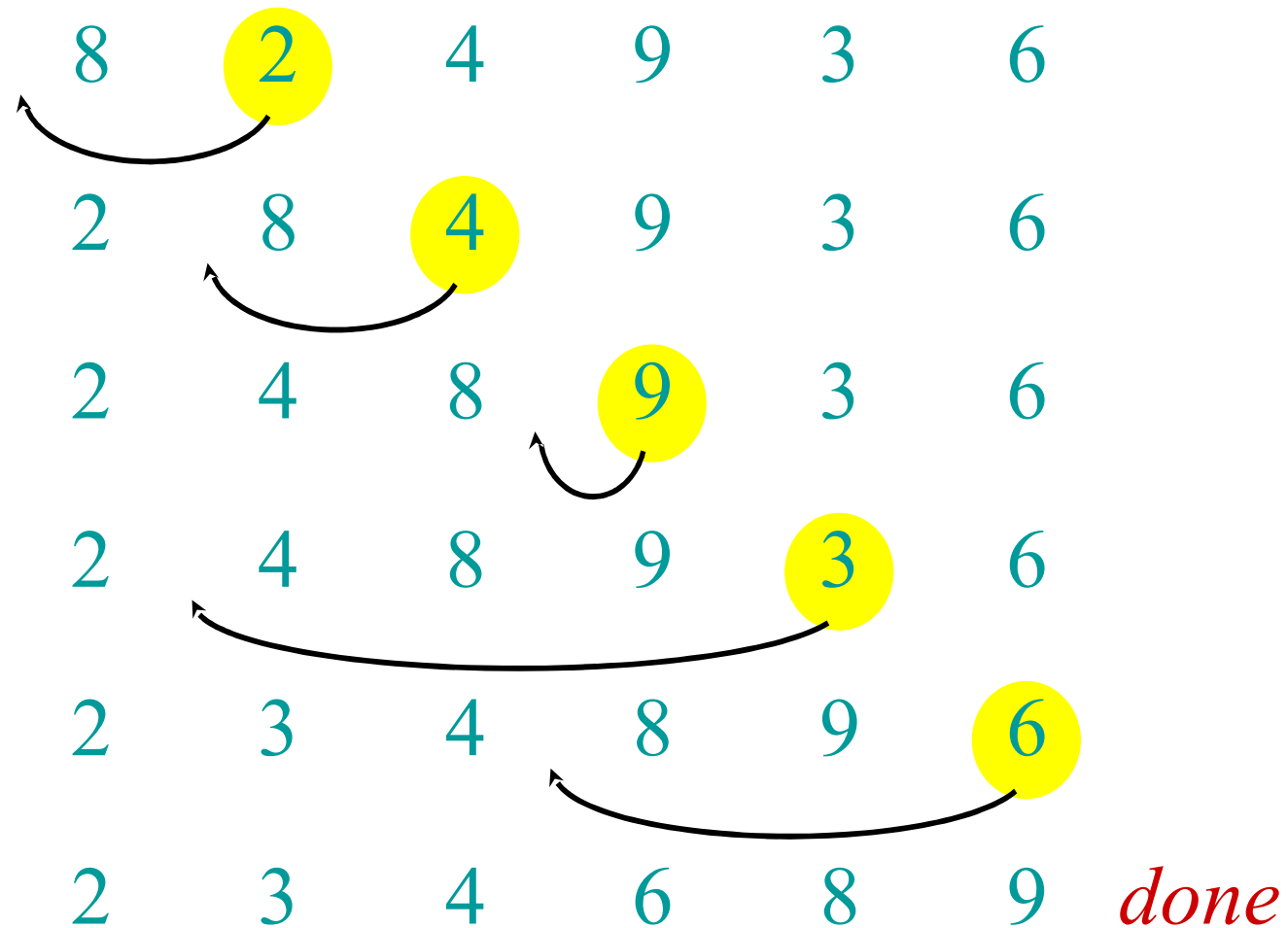


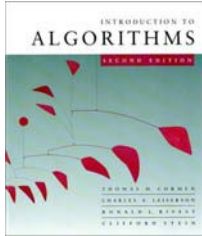
Example of insertion sort





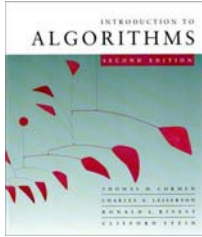
Example of insertion sort





Running time

- The running time depends on the input: an already sorted sequence is easier to sort.
- Parameterize the running time by the size of the input, since short sequences are easier to sort than long ones.
- Generally, we seek upper bounds on the running time, because everybody likes a guarantee.



Kinds of analyses

Worst-case: (usually)

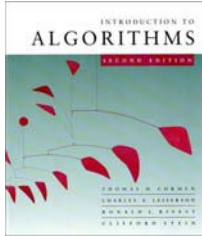
- $T(n)$ = maximum time of algorithm on any input of size n .

Average-case: (sometimes)

- $T(n)$ = expected time of algorithm over all inputs of size n .
- Need assumption of statistical distribution of inputs.

Best-case: (bogus)

- Cheat with a slow algorithm that works fast on *some* input.



Machine-independent time

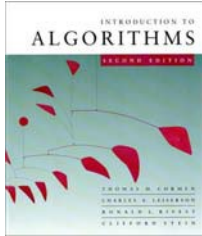
What is insertion sort's worst-case time?

- It depends on the speed of our computer:
 - relative speed (on the same machine),
 - absolute speed (on different machines).

BIG IDEA:

- Ignore machine-dependent constants.
- Look at *growth* of $T(n)$ as $n \rightarrow \infty$.

“Asymptotic Analysis”



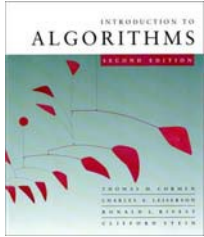
⊕-notation

Math:

$\Theta(g(n)) = \{ f(n) : \text{there exist positive constants } c_1, c_2, \text{ and } n_0 \text{ such that } 0 \leq c_1 g(n) \leq f(n) \leq c_2 g(n) \text{ for all } n \geq n_0 \}$

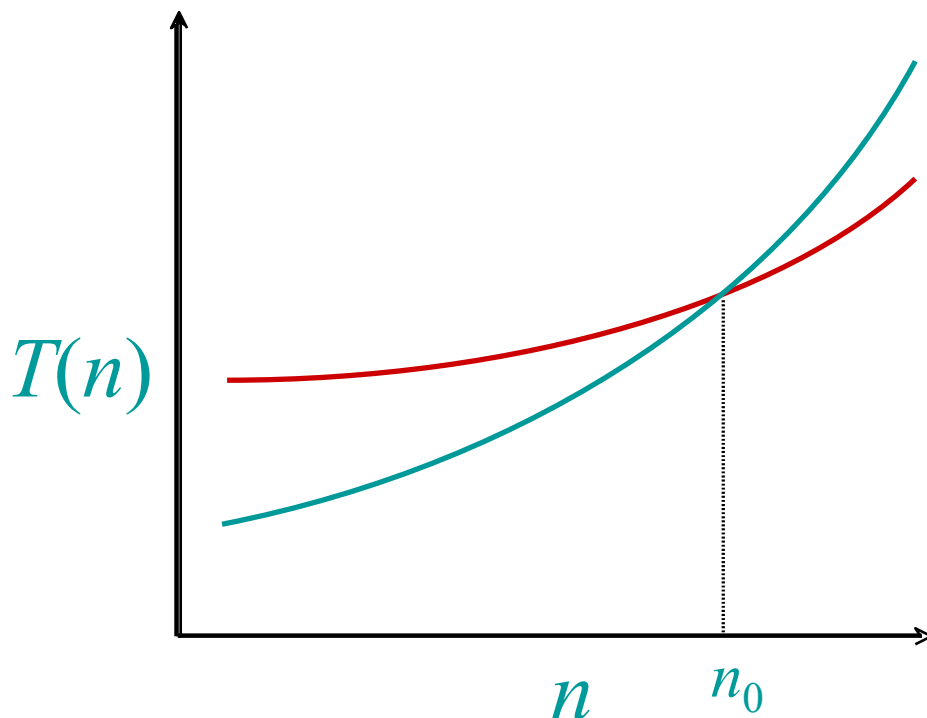
Engineering:

- Drop low-order terms; ignore leading constants.
- Example: $3n^3 + 90n^2 - 5n + 6046 = \Theta(n^3)$



Asymptotic performance

When n gets large enough, a $\Theta(n^2)$ algorithm *always* beats a $\Theta(n^3)$ algorithm.



- We shouldn't ignore asymptotically slower algorithms, however.
- Real-world design situations often call for a careful balancing of engineering objectives.
- Asymptotic analysis is a useful tool to help to structure our thinking.

Insertion Sort Analysis

$$\sum_{i=1}^n i = 1 + 2 + \dots + (n-1) + n$$

$$\sum_{i=1}^n i = n + (n-1) + \dots + 2 + 1$$

$$2 \sum_{i=1}^n i = (n+1) + (n+1) + \dots + (n+1) + (n+1)$$

$$\sum_{i=1}^n i = \frac{n(n+1)}{2}$$

Review in Appendix A

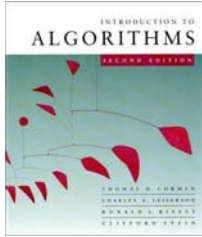
Insertion Sort Analysis

	<i>cost</i>	<i>times</i>
INSERTION-SORT(<i>A</i>)		
1 for $j \leftarrow 2$ to $\text{length}[A]$	c_1	n
2 do $\text{key} \leftarrow A[j]$	c_2	$n - 1$
3 ▷ Insert $A[j]$ into the sorted sequence $A[1 \dots j - 1]$.	0	$n - 1$
4 $i \leftarrow j - 1$	c_4	$n - 1$
5 while $i > 0$ and $A[i] > \text{key}$	c_5	$\sum_{j=2}^n t_j$
6 do $A[i + 1] \leftarrow A[i]$	c_6	$\sum_{j=2}^n (t_j - 1)$
7 $i \leftarrow i - 1$	c_7	$\sum_{j=2}^n (t_j - 1)$
8 $A[i + 1] \leftarrow \text{key}$	c_8	$n - 1$

Average case: all permutations equally likely

$$\sum_{j=2}^n t_j = \sum_{j=2}^n \frac{j}{2}$$

$$T(n) = an^2 + bn + c = \Theta(n^2)$$



Insertion sort analysis

Worst case: Input reverse sorted.

$$T(n) = \sum_{j=2}^n \Theta(j) = \Theta(n^2) \quad [\text{arithmetic series}]$$

Average case: All permutations equally likely.

$$T(n) = \sum_{j=2}^n \Theta(j/2) = \Theta(n^2)$$

Is insertion sort a fast sorting algorithm?

- Moderately so, for small n .
- Not at all, for large n .

Insertion Sort Analysis

- What about **space**?
- Insertion sorts “**in place**” as it does not copy the array anywhere
- It only takes a constant amount of extra storage, independent of n
- Therefore $S(n) = \Theta(1)$

Merge Sort

- **Divide-and-Conquer**

- *Divide* the problem into a number of sub-problems
- *Conquer* the smaller problems
- *Combine* the results of the sub-problems into a solution for the big problem

```
MERGE-SORT( $A, p, r$ )
```

```
1  if  $p < r$ 
```

```
2      then  $q \leftarrow \lfloor (p + r) / 2 \rfloor$ 
```

```
3          MERGE-SORT( $A, p, q$ )
```

```
4          MERGE-SORT( $A, q + 1, r$ )
```

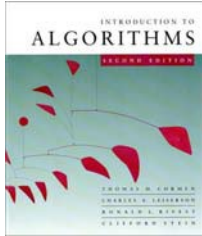
```
5          MERGE( $A, p, q, r$ )
```

Merge Sort

- **Divide-and-Conquer**

- *Divide* the problem into a number of sub-problems
- *Conquer* the smaller problems
- *Combine* the results of the sub-problems into a solution for the big problem

```
void merge_sort(vector<int>& A, int p, int r) {  
    if (p >= r) return;  
  
    int q = (p + r) / 2;  
  
    merge_sort(A, p, q);  
    merge_sort(A, q+1, r);  
  
    merge(A, p, q, r);  
}
```

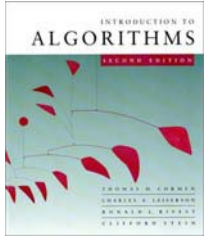


Merge sort

MERGE-SORT $A[1 \dots n]$

1. If $n = 1$, done.
2. Recursively sort $A[1 \dots \lfloor n/2 \rfloor]$ and $A[\lfloor n/2 \rfloor + 1 \dots n]$.
3. “*Merge*” the 2 sorted lists.

***Key subroutine:* MERGE**



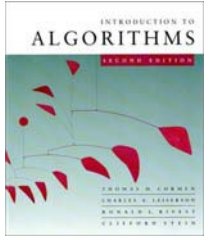
Merging two sorted arrays

20 12

13 11

7 9

2 1

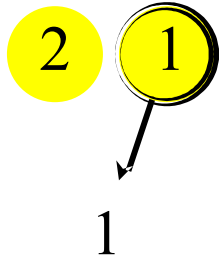


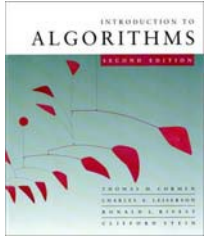
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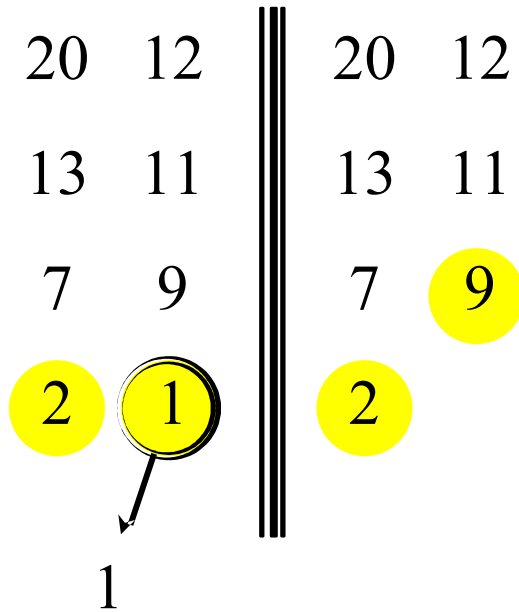
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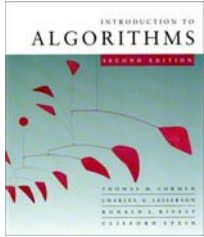
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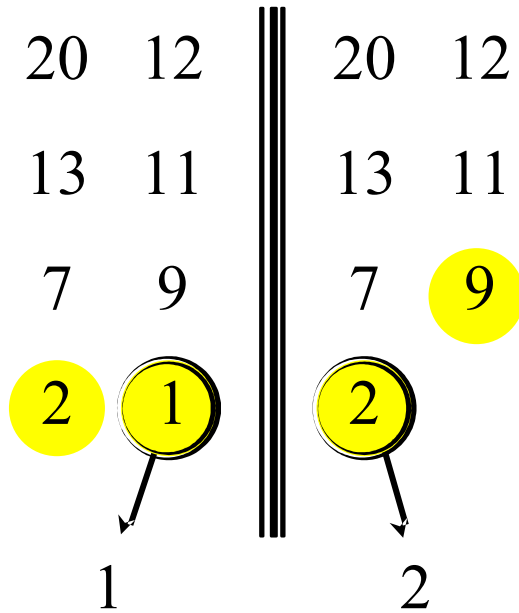


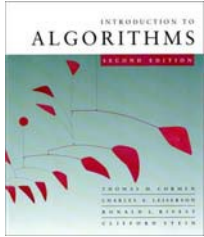
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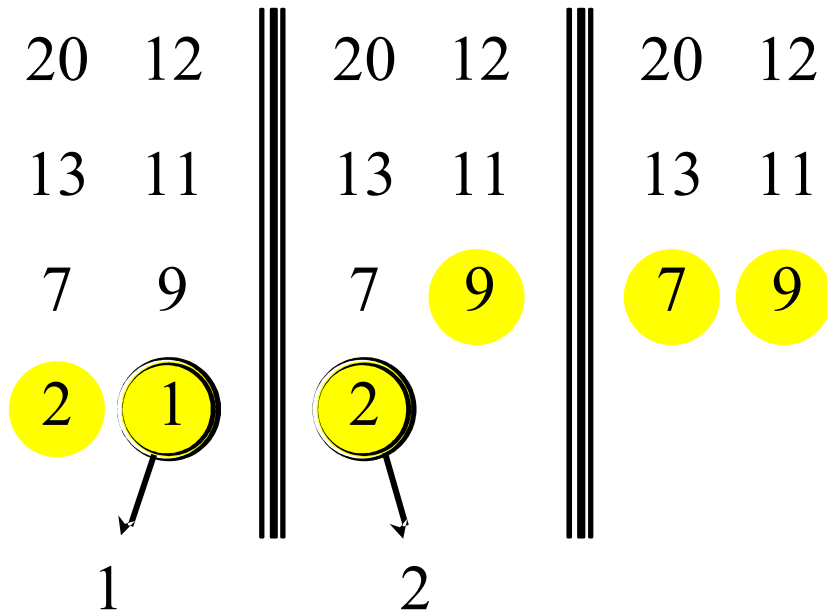


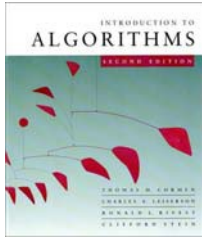
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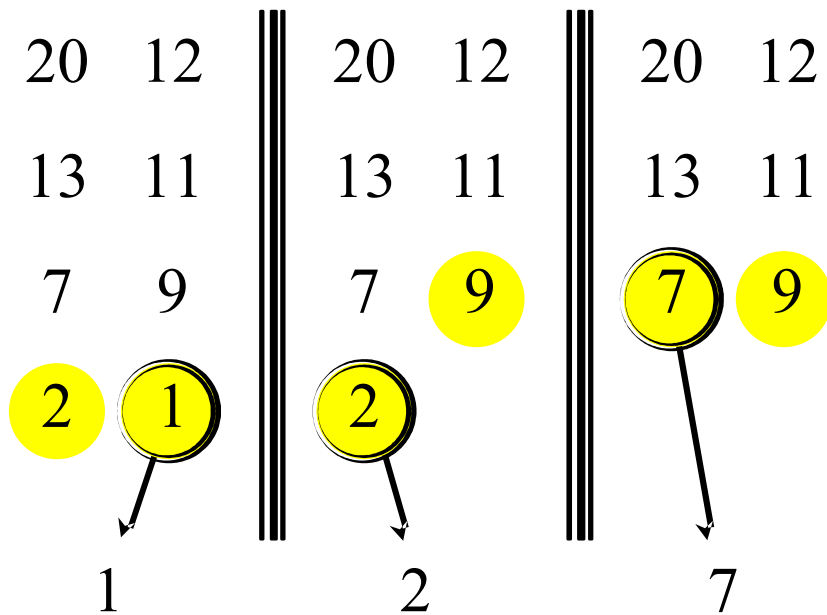


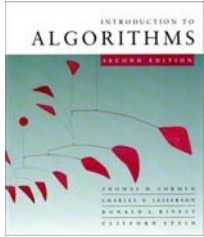
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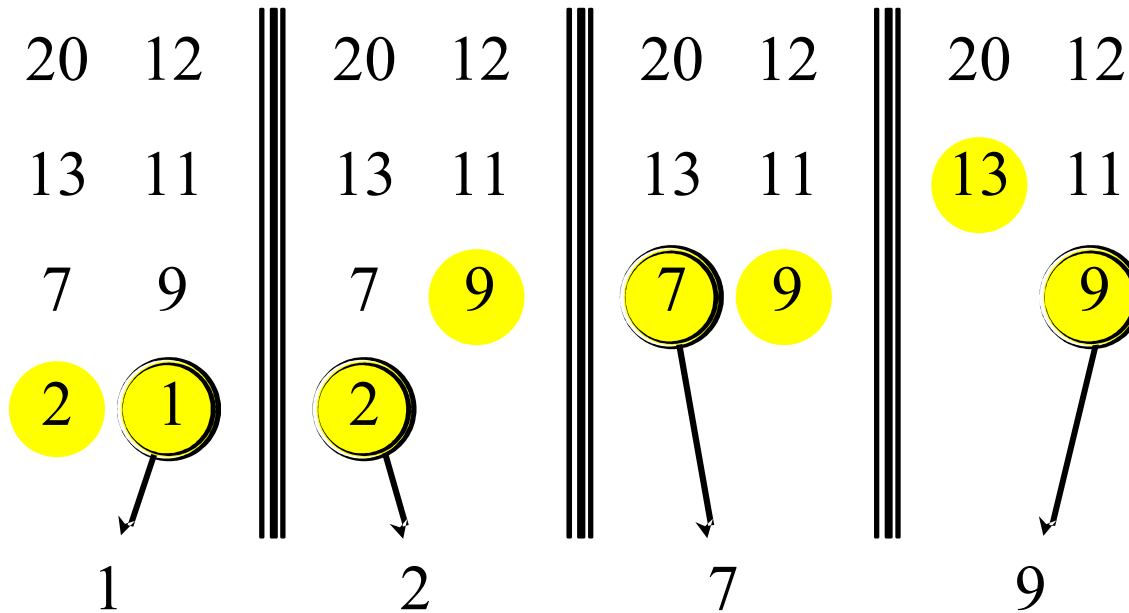


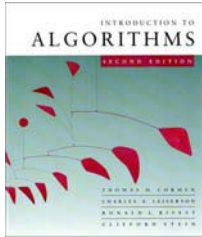
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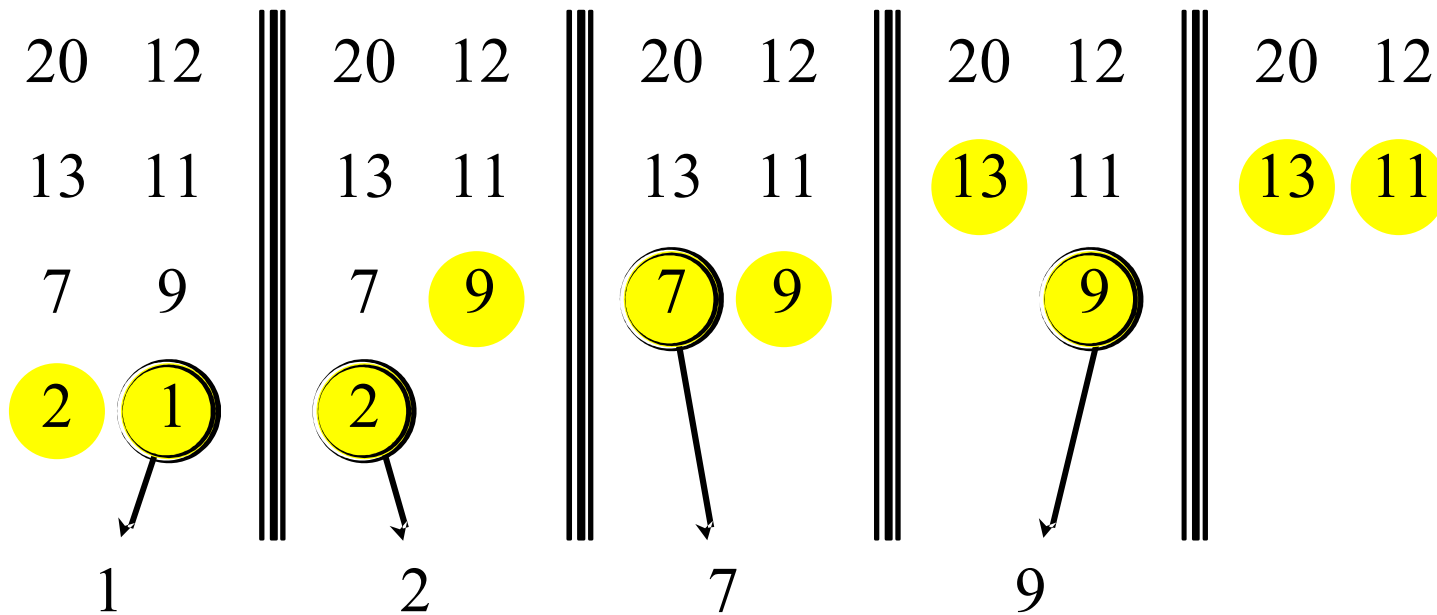


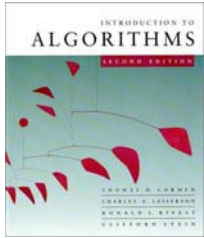
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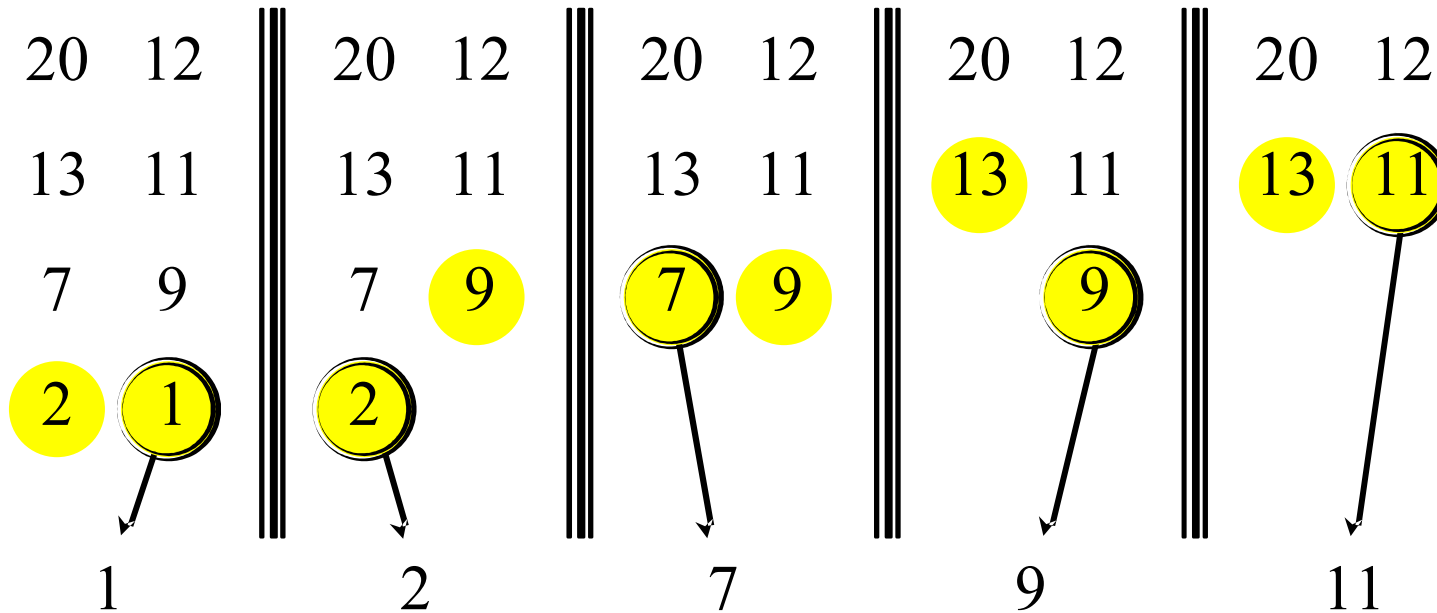


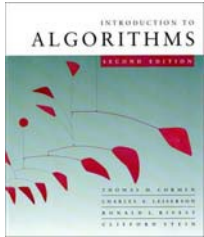
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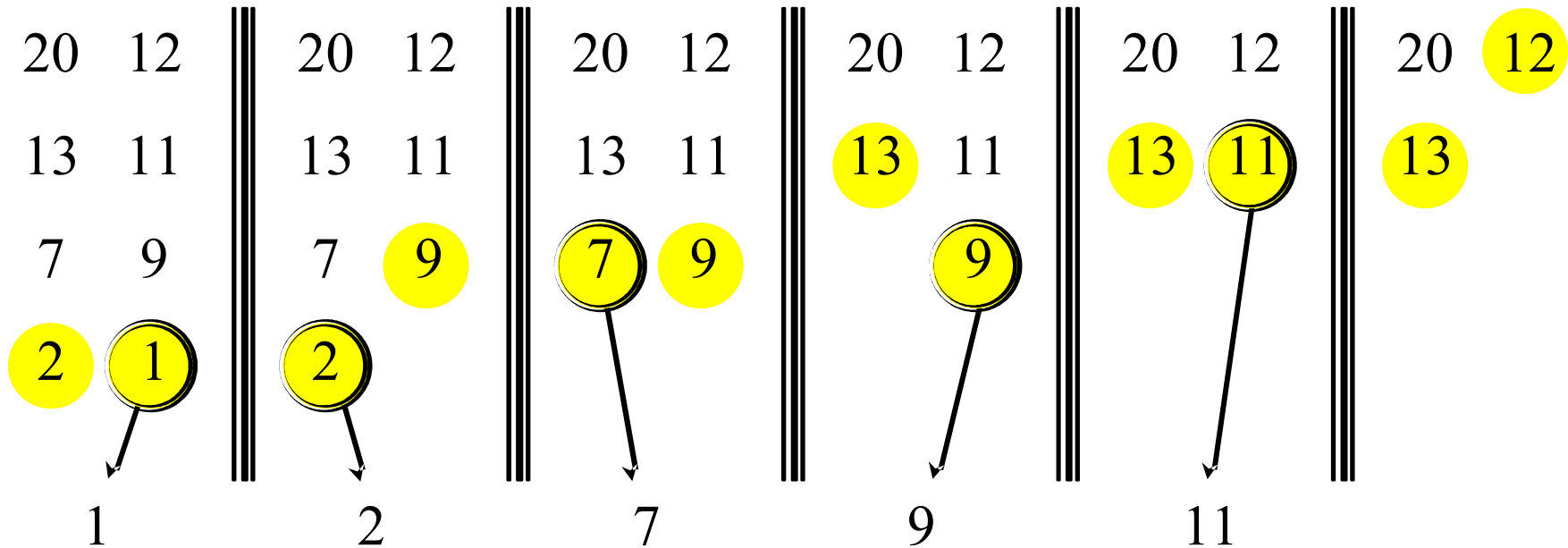


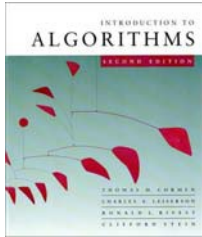
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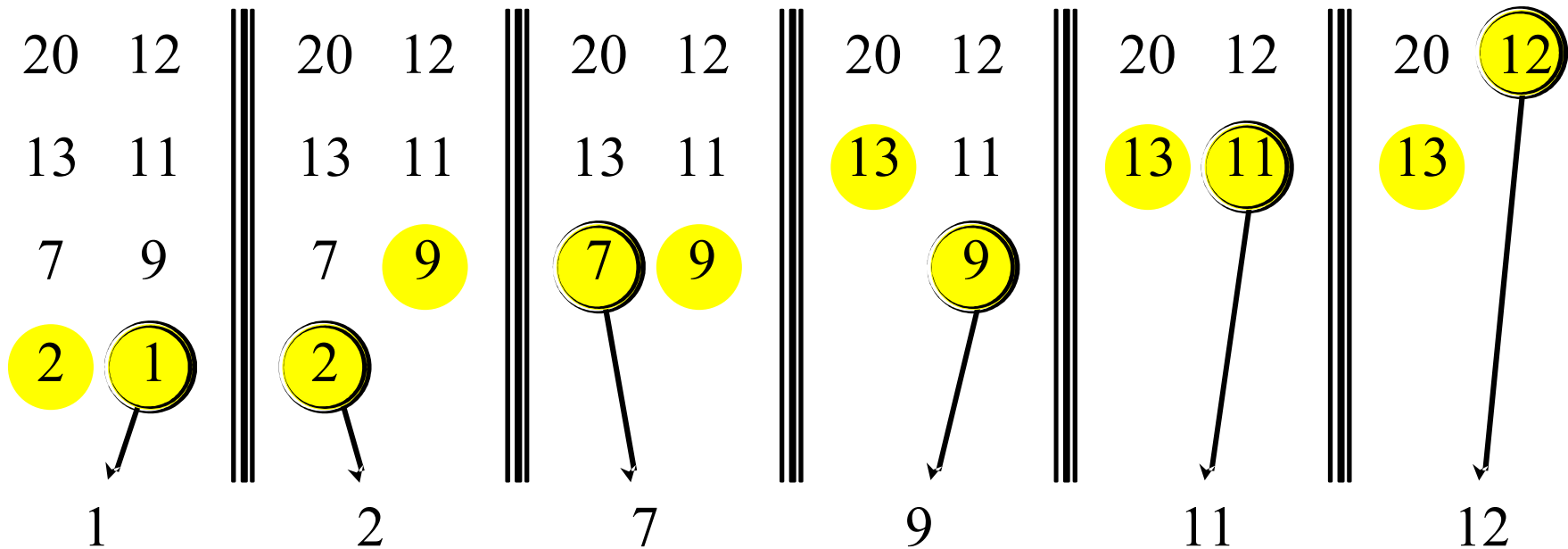


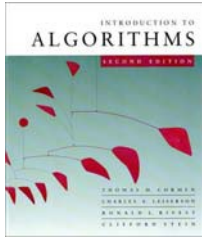
Merging two sorted arrays



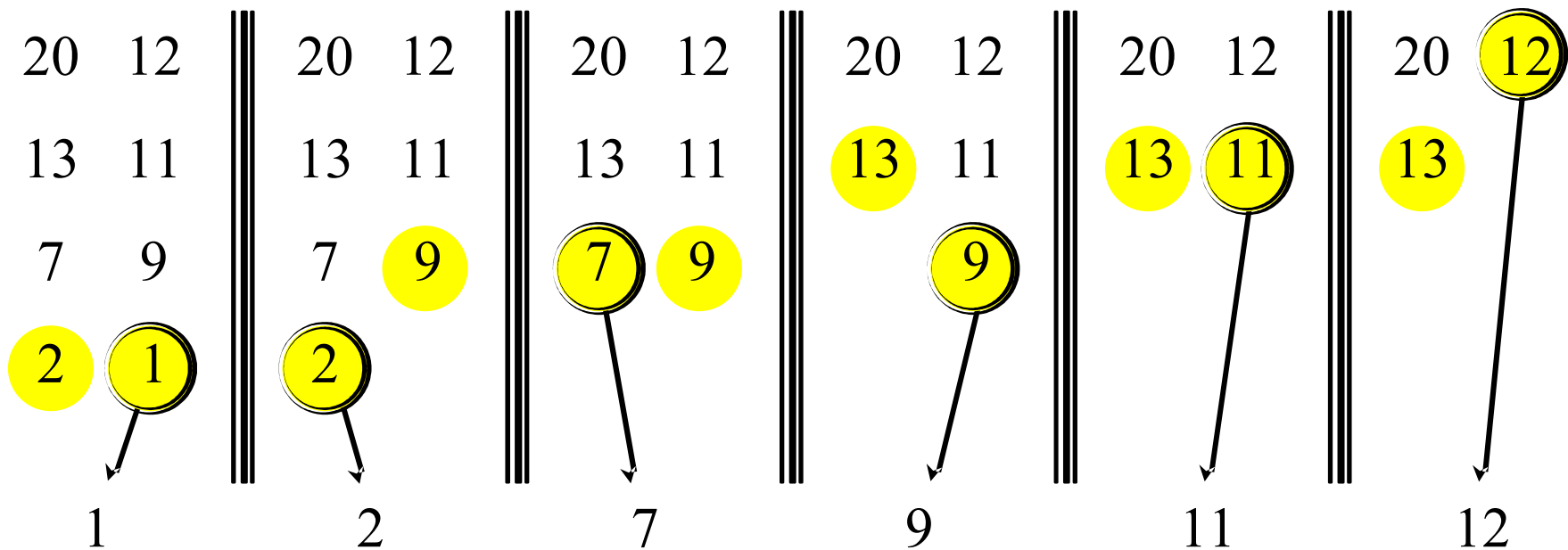


Merging two sorted arrays





Merging two sorted arrays



Time = $\Theta(n)$ to merge a total of n elements (linear time).

Merge

MERGE(A, p, q, r)

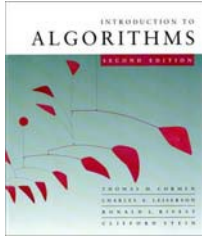
```
1   $n_1 = q - p + 1$ 
2   $n_2 = r - q$ 
3  let  $L[1..n_1 + 1]$  and  $R[1..n_2 + 1]$  be new arrays
4  for  $i = 1$  to  $n_1$ 
5       $L[i] = A[p + i - 1]$ 
6  for  $j = 1$  to  $n_2$ 
7       $R[j] = A[q + j]$ 
8   $L[n_1 + 1] = \infty$ 
9   $R[n_2 + 1] = \infty$ 
10  $i = 1$ 
11  $j = 1$ 
12 for  $k = p$  to  $r$ 
13     if  $L[i] \leq R[j]$ 
14          $A[k] = L[i]$ 
15          $i = i + 1$ 
16     else  $A[k] = R[j]$ 
17          $j = j + 1$ 
```

← compute sizes

← copy arrays to be merged

← adds "sentinel"

← merge



Analyzing merge sort

Abuse

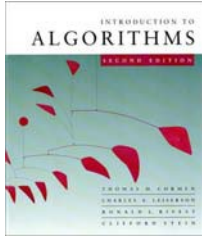
$T(n)$		MERGE-SORT $A[1 \dots n]$
$\Theta(1)$		1. If $n = 1$, done.
$2T(n/2)$		2. Recursively sort $A[1 \dots \lceil n/2 \rceil]$ and $A[\lceil n/2 \rceil + 1 \dots n]$.
$\Theta(n)$		3. “Merge” the 2 sorted lists

Sloppiness: Should be $T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor)$,
but it turns out not to matter asymptotically.

Recurrence for Merge Sort

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1; \\ 2T(n/2) + \Theta(n) & \text{if } n > 1. \end{cases}$$

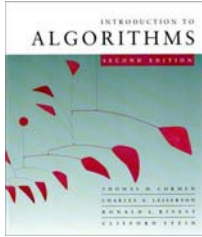
- Next we need to solve this recurrence relation i.e. find $T(n)$ as a function of n without $T(n/2)$



Recurrence for merge sort

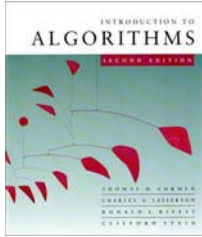
$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1; \\ 2T(n/2) + \Theta(n) & \text{if } n > 1. \end{cases}$$

- We shall usually omit stating the base case when $T(n) = \Theta(1)$ for sufficiently small n , but only when it has no effect on the asymptotic solution to the recurrence.
- CLRS and Lecture 2 provide several ways to find a good upper bound on $T(n)$.



Recursion tree

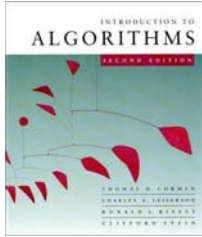
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



Recursion tree

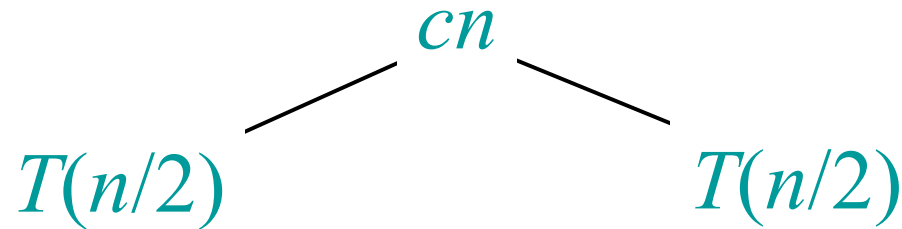
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

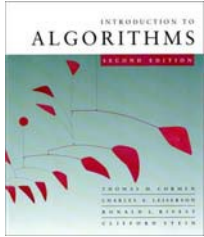
$$T(n)$$



Recursion tree

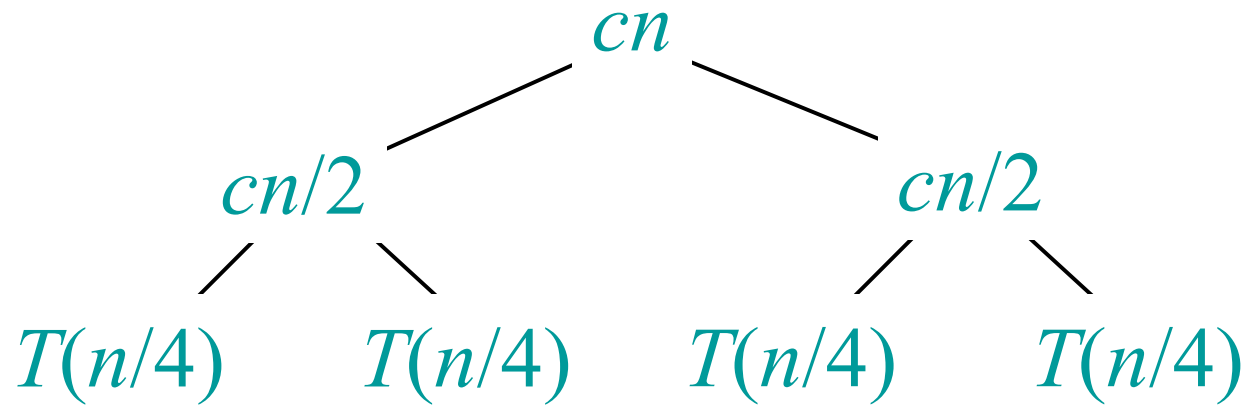
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

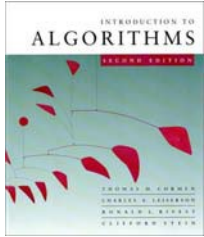




Recursion tree

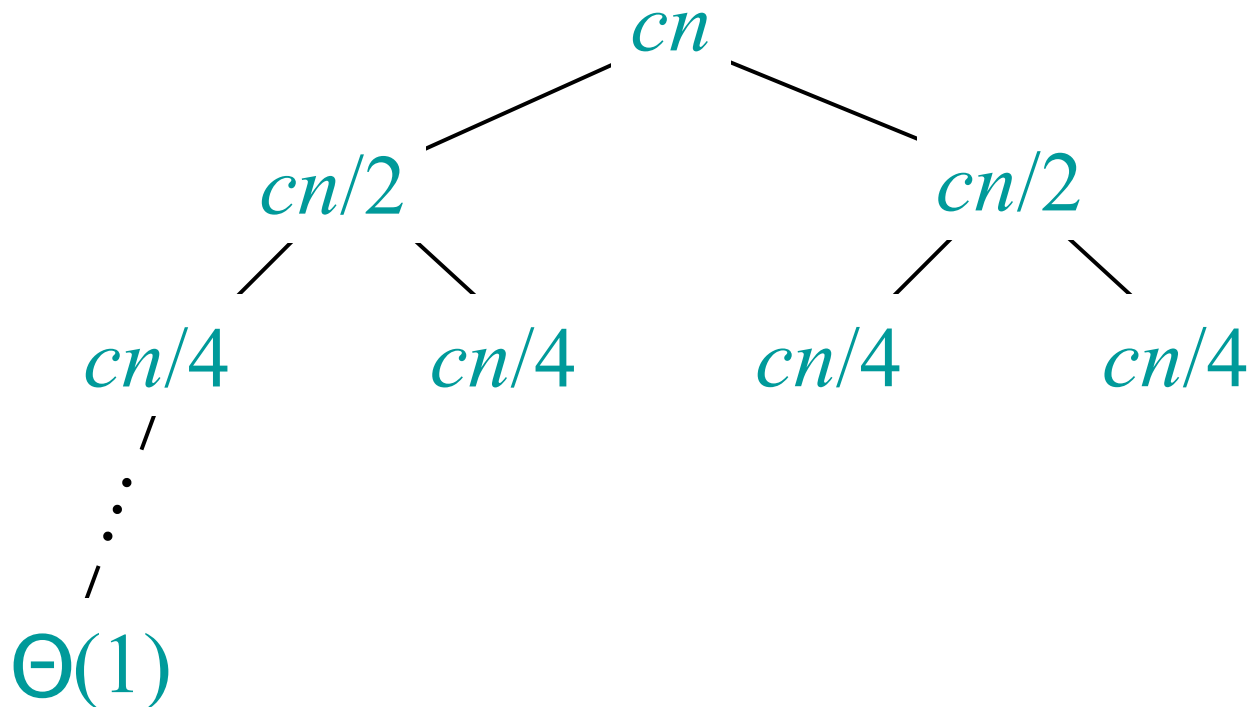
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

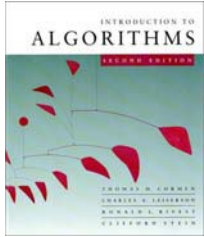




Recursion tree

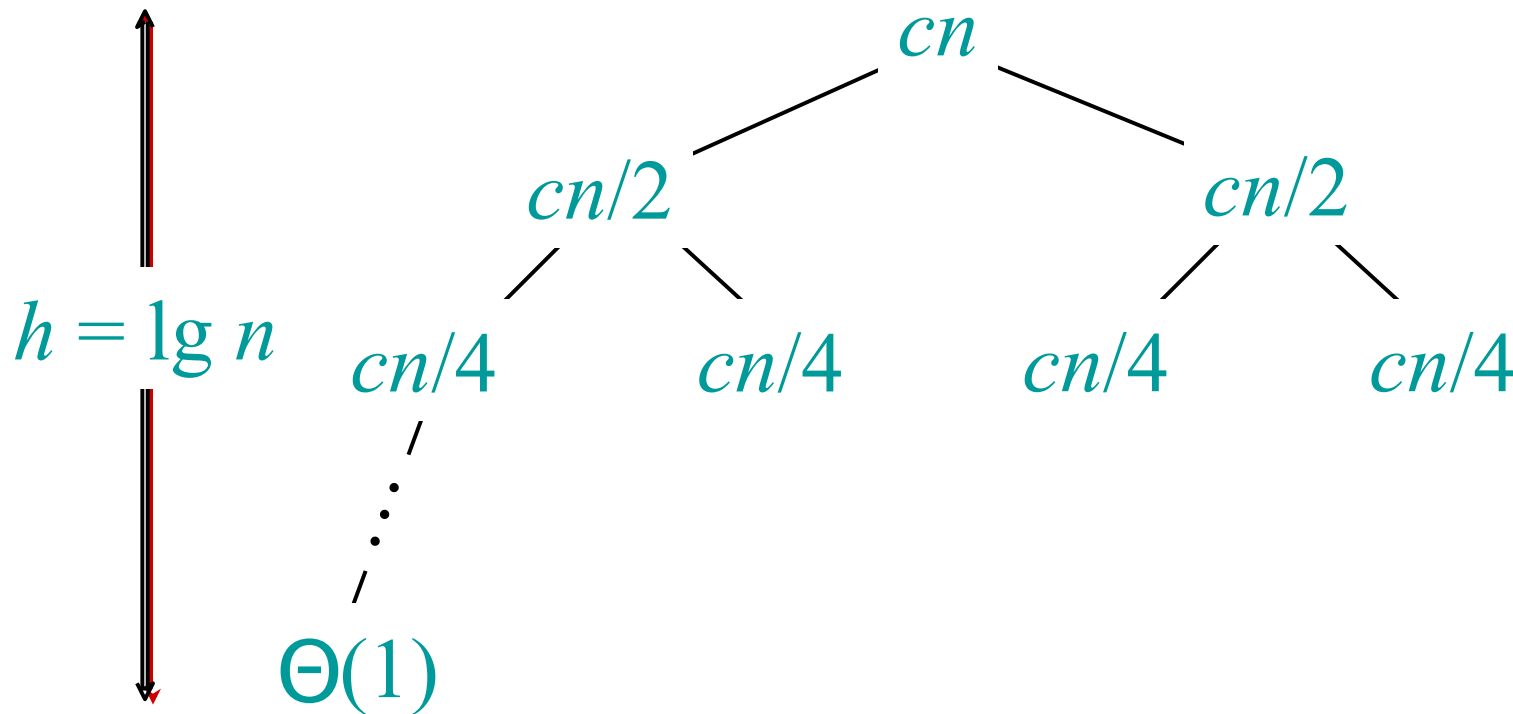
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

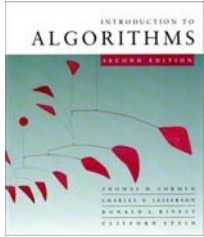




Recursion tree

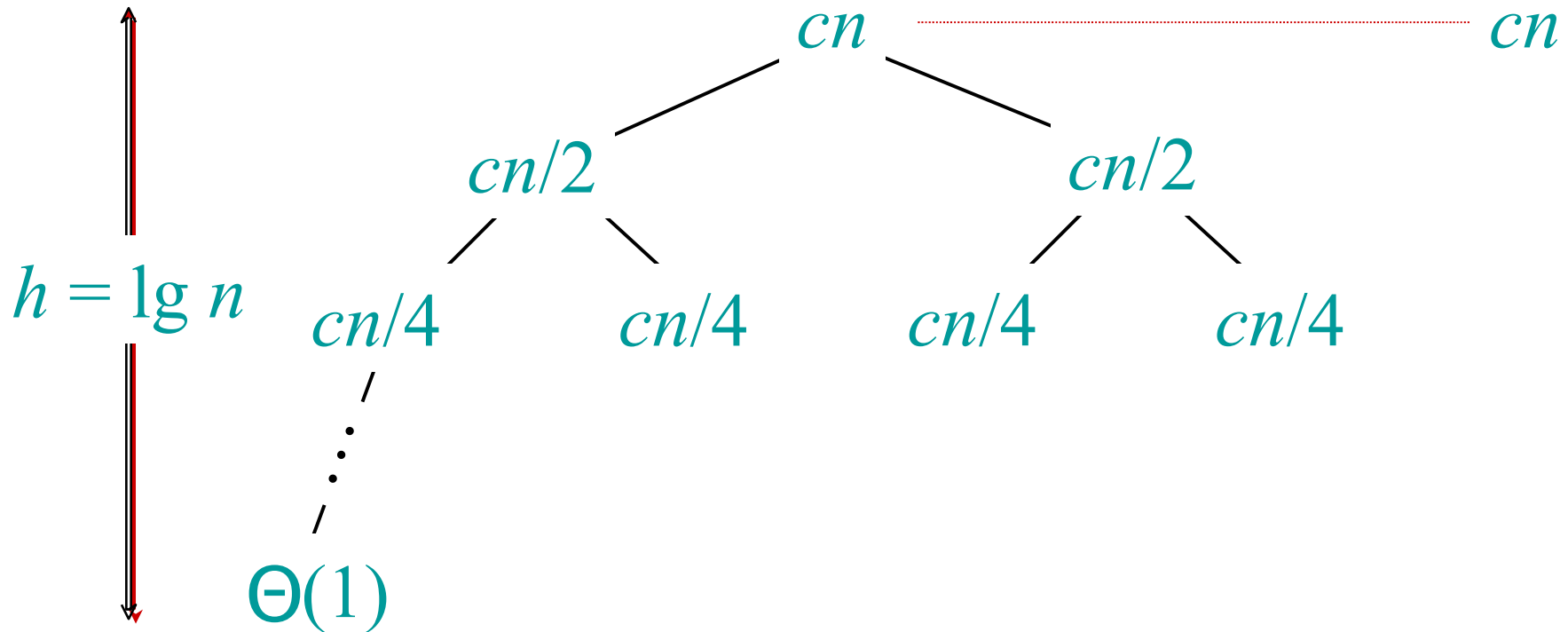
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

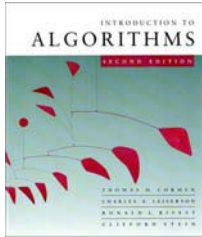




Recursion tree

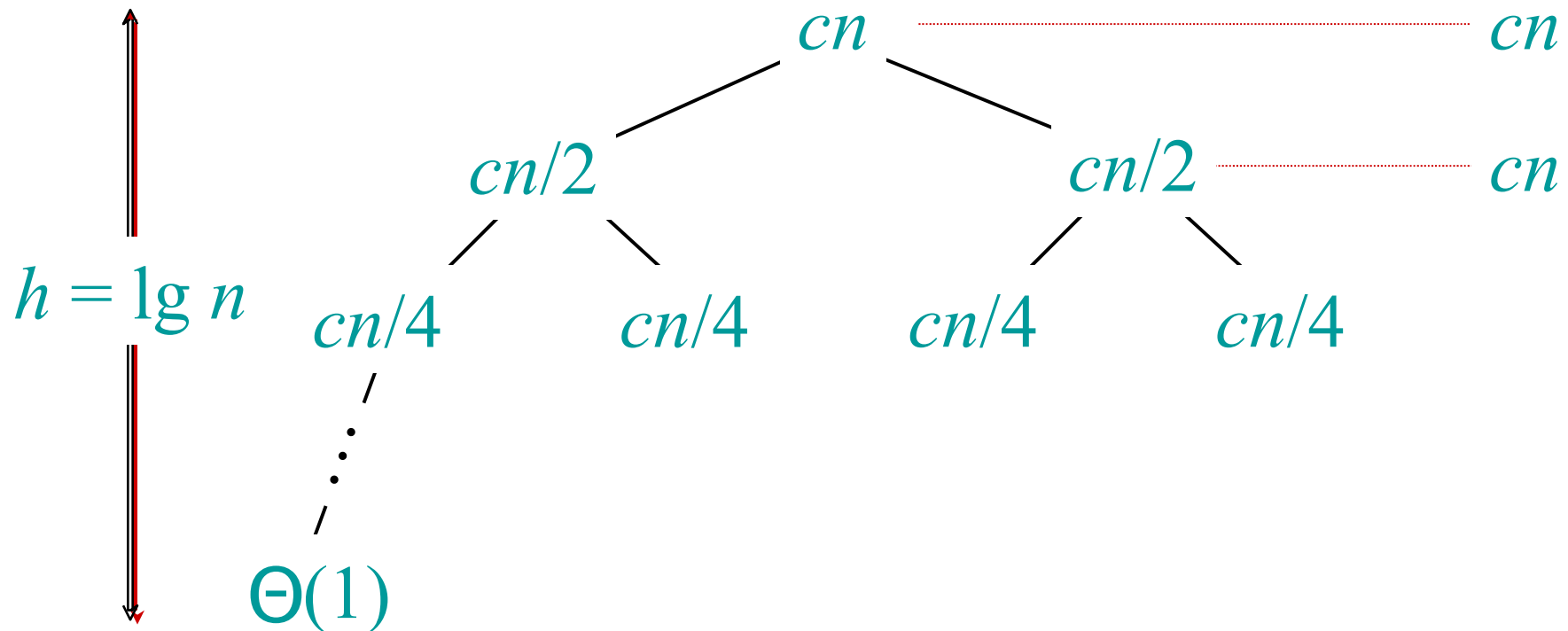
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

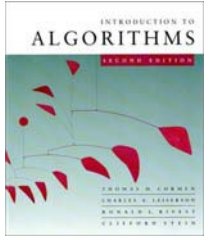




Recursion tree

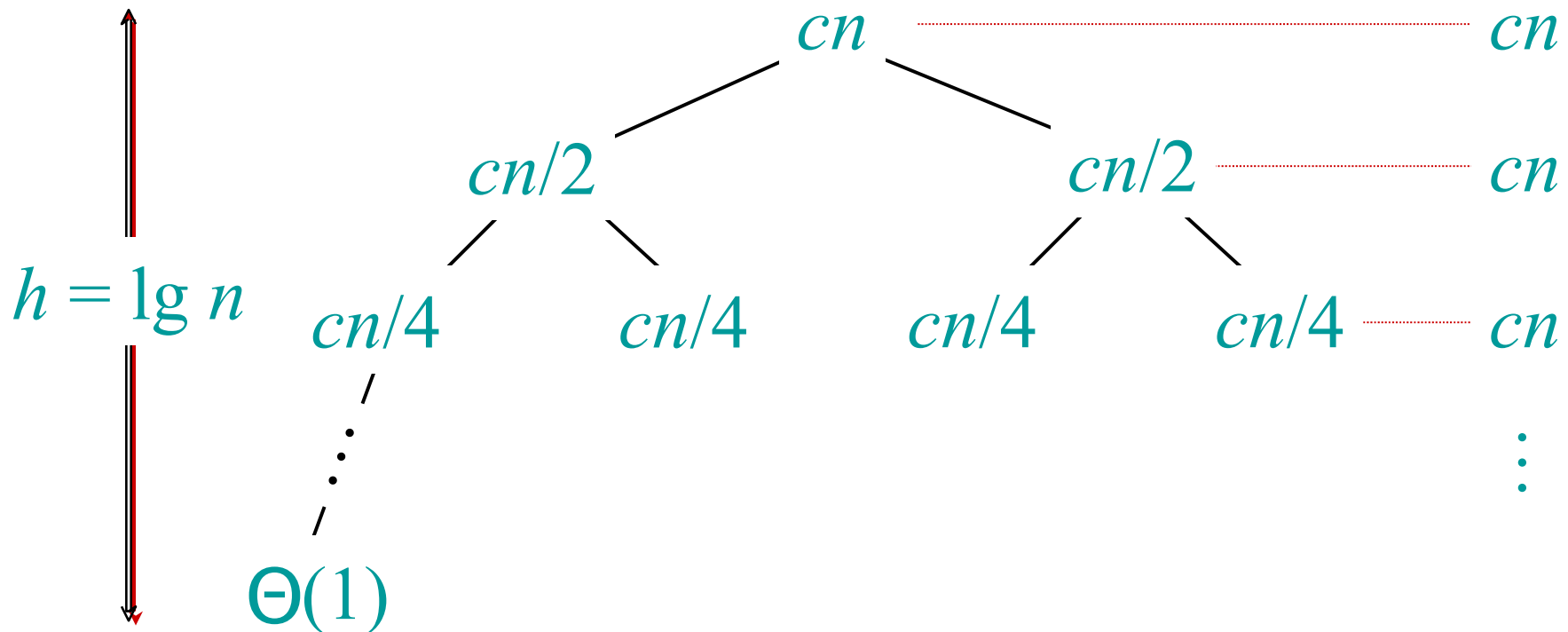
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

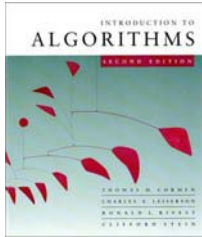




Recursion tree

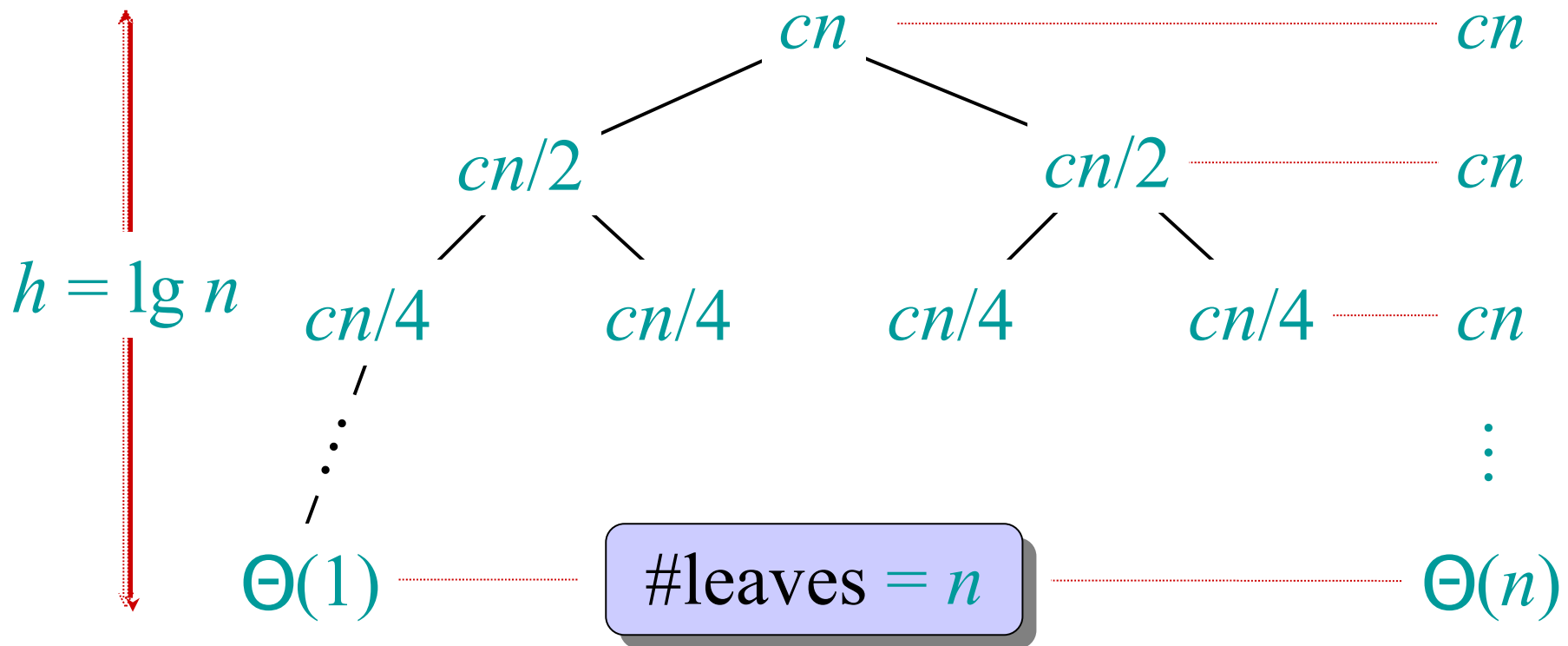
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

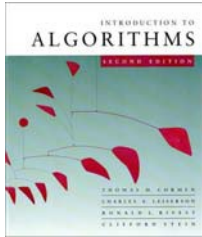




Recursion tree

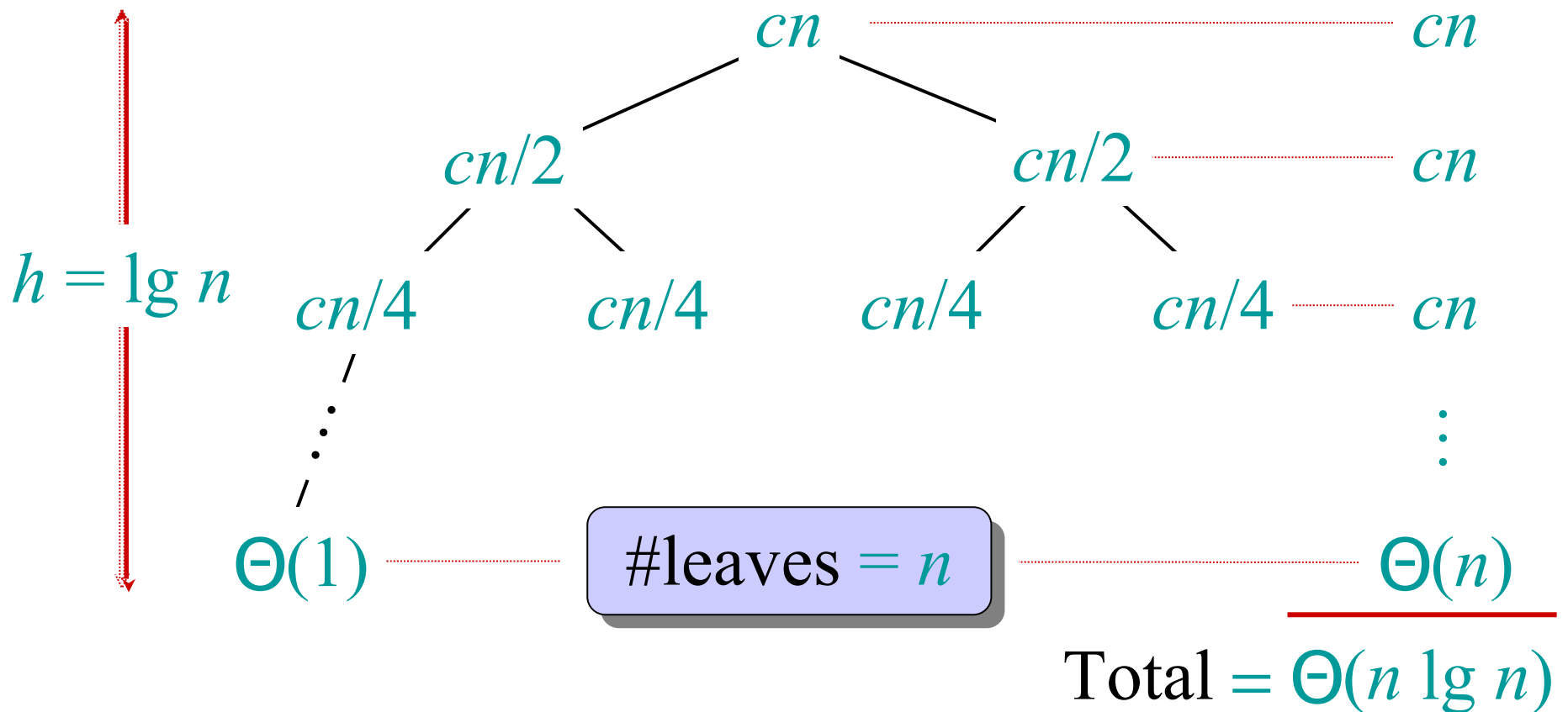
Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.





Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



Merge Sort Analysis

- What about space?
- Merge Sort does **not** sort “in place” as it needs temporary space for the “Merge” subroutine
- It needs space: $S(n) = \Theta(n)$

Conclusion

- Insertion Sort:

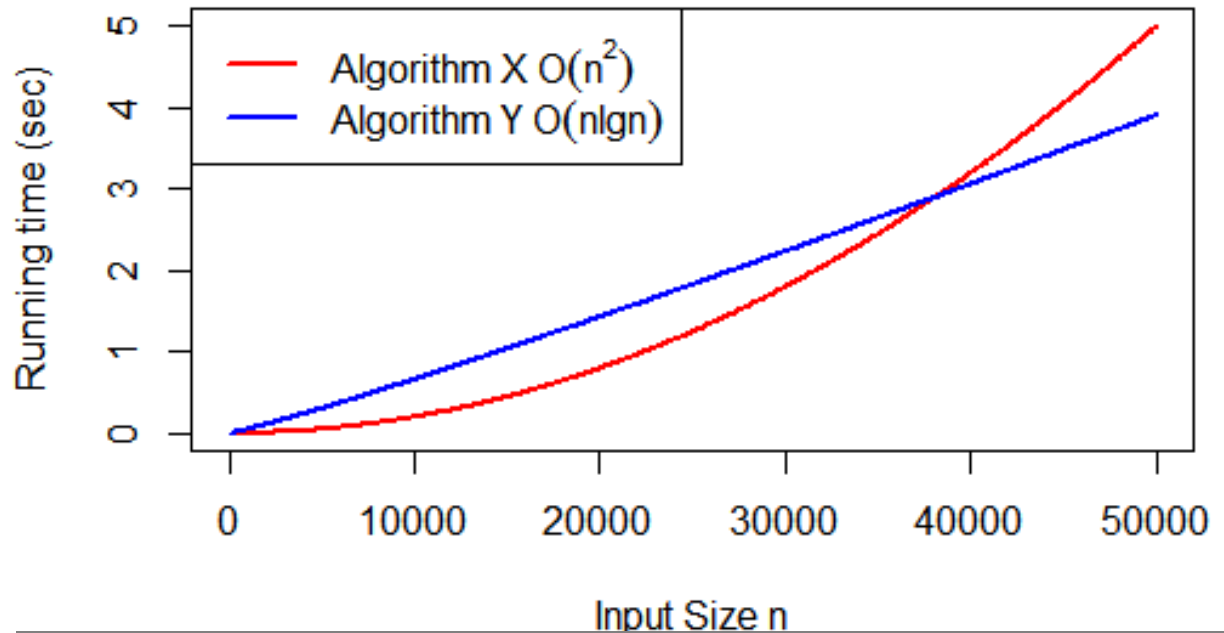
- $T(n) = \Theta(n^2)$

- $S(n) = \Theta(1)$

- Merge Sort:

- $T(n) = \Theta(n \lg n)$

- $S(n) = \Theta(n)$



- Insertion sort better for smaller n, merge sort for larger n

Recap

- Insertion Sort
- Merge Sort
- Asymptotic Analysis
- Recurrences
- Next: More on recurrences and asymptotic analysis